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Vector Mechanics for Engineers: Statics Equilibrium of a Rigid Body in Two Dimensions 4 - 10 • For known forces and moments that act on a two-dimensional structure, the following are true: Fz = 0 M x = M y = 0 M z = M O • Equations of equilibrium become  $\sum Fx = 0$   $\sum Fy = 0$   $\sum M$  A = 0 where A can be any point in the plane of the body.

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Vector Mechanics for Engineers: Statics Edition. 4 - 15. Equilibrium of a Two-Force Body • Consider a plate subjected to two forces . F. 1 . and . F. 2 • For static equilibrium, the sum of moments about . A . must be zero. The moment of . F. 2 . must be zero. It follows that the line of action of . F. 2 . must pass through . A. • Similarly, the line of action of . F. 1 . must pass

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• Differential vector is the dr particle displacement. r • Work of the force is F dx F dyF dz Fds dU F dr = x + y + z = x + z + z = x + z + z + z + z = x + z + z + z + z + z + z + z +

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EditionEighth Vector Mechanics for Engineers: Dynamics Sample Problem 15.8 • The angular accelerations are determined by simultaneously solving the component equations for rrr aD = aB + aD B rrr 2 r aD =  $\alpha$  DE  $\times$  rD -  $\omega$  DE rD rrrrr =  $\alpha$  DE k  $\times$  (- 17i + 17 j) - (11.29) (- 17i + 17 j) 2 rr rr = -17 $\alpha$  DE i - 17 $\alpha$  DE j + 2170i - 2170 j rrr 2 r 2 rr aB =  $\alpha$  AB  $\times$  rB -  $\omega$  AB rB = 0 - (20) (8i + 14 j) rr = -3200i + 5600 j rrr 2 r aD B =  $\alpha$  BD  $\times$  rB D ...

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Determinegraphically the magnitude and direction of ...

## Two forces are applied as shown to a bracket support ...

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